

Moving Image Perception

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Moving Image Perception

- Human Vision Modeling
- Video Frequency Content
- Spatiotemporal HVS Models
- Video Quality Assessment





Human Vision Modeling

- One of digital image and video processing aims is image quality improvement.
- *Human Visual System* (*HVS*) modeling is difficult, because of its complex structure.





Human Vision Modeling



- Human eye: spherical shape with a diameter of 20 mm.
- Light enters the *pupil* of the *iris* (diameter 2 8 mm).
- It passes through *lens*, *vitreous humour* and on the *retina*.





Human eye.



Human Vision Modeling

Retina light detectors: cones and rods.

- Cones: sensitive to color.
 - Photopic (high brightness, daylight) vision.
- Rods: sensitive to light intensity, not color.
 - They create a general idea of the visual content.
 - Scotopic (night) vision.





Human visual system model.



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- A frequency F is linked with angular frequency $\Omega = 2\pi F$.
- Spatial frequencies (video content changes along *x*, *y* axes):

•
$$\Omega_x = 2\pi F_x$$
 and $\Omega_y = 2\pi F_y$



2D sinusoidal signals: a)
$$(F_x, F_y) = (0,6)$$
; b) $(F_x, F_y) = (10,4)$.



Spatial frequencies F_x , F_y :

- They show spatial luminance changes on the image plane.
- Local frequency vector $\mathbf{\Omega} = [\Omega_x, \Omega_y]^T$ is colinear to local image content change direction (perpendicular to edge direction).
- Spatial frequencies can be defined along different orthogonal axes than (x, y).
- They are measured in cycles per unit length:
 - e.g., a 2D sinusoidal spatial pattern $f(x,y) = \sin(20\pi y)$ has a frequency (0,10).



Temporal Frequency *F*_t:

- Video signal: moving image (2D video frames changing over time).
- The temporal frequency F_t depends on image content motion.
- The video content motion is due to:
 - camera motion and/or
 - object(s) motion.





Constant velocity **2D linear object motion**:

- $f_0(x,y) = f(x,y,0)$: object image at time t = 0.
- $\mathbf{v} = [v_x, v_y]^T$: object motion vector.
- v_x , v_y : horizontal/vertical speed.

Object image at time t (for homogeneous image background):

$$f(x, y, t) = f(x - v_x t, y - v_y t, 0) = f_0(x - v_x t, y - v_y t).$$







Linear constant 2D object motion.





Spatiotemporal Fourier Transform:

$$\begin{split} F\big(\Omega_x,\Omega_y,\Omega_t\big) &= \iiint f(x,y,t)e^{-i\big(\Omega_x x + \Omega_y y + \Omega_t t\big)} \, dx \, dy \, dt = \\ F_0\big(\Omega_x,\Omega_y\big)\delta\big(\Omega_t + \Omega_x v_x + \Omega_y v_y\big). \end{split}$$

 δ : delta function.

- Non-zero spectrum $F(\Omega_x, \Omega_y, \Omega_t)$ only on the plane: $\Omega_t + \Omega_x v_x + \Omega_y v_y = 0.$
- Temporal frequency due to object motion:

$$\Omega_t = -\Omega_x v_x - \Omega_y v_y = -\mathbf{\Omega}^T \mathbf{v}.$$





- When $\Omega_x = \Omega_y = 0$ (image is blank, has no content), then $\Omega_t = 0$, regardless of image plane motion.
- Temporal frequency $\Omega_t = 0$, if:
 - Motion vector \boldsymbol{v} is orthogonal to the spatial frequency vector $\boldsymbol{\Omega} = [\Omega_x, \Omega_y]^T$ or
 - $\Omega = 0$ (no motion).





V

Motion vector perpendicular to local image frequency vector.



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- For the *spatiotemporal modelling* of human vision, dynamic models of neurons must be used:
 - It is particularly difficult.
- The eye is a dynamic system:
 - pupil diameter changes with light intensity,
 - the human eye can rotate and perform smooth pursuit movements.
- Spatiotemporal image perception experiments.





Temporal sensitivity of the human vision:

- HVS temporal frequency response refers to HVS sensitivity to temporal video content variations.
- Display flicker.





Kelly experiments: determination of the necessary video frame rate (fps).

 Observers were presented a flat screen whose luminance changed sinusoidally:

 $f(x, y, t) = C(1 + s \cos 2\pi F_t t).$

- C: constant luminance,
- F_t: temporal frequency,
- s intensity modulation level.



- Intensity modulation levels *s* were changed for constant luminance *C*.
- Observers were asked to identify lowest observable modulation level s_{min} .

• Observer **sensitivity** to temporal luminance variations at frequency F_t :

 $s_e = 1/s_{min}$.





Contrast Sensitivity Function (**CSF**) $s_e(C, F_t)$.

- *Troland*: a unit to describe the light intensity entering the eye retina.
- CSF $s_e(C, F_t)$ is a band-pass function of both C, F_t .







- Sharp reduction after a cutoff frequency.
- Peak frequency increases with the average image brightness.
- Human eye has low sensitivity to high temporal frequencies because it retains the sense of an image for a short time (*vision persistence*).
 - It is caused by the temporal integration of the incoming light energy.





- **Block's law** states that the integration period is inversely proportional to that of the light intensity.
- The brighter the source is, the shorter is the retention period.
- Brighter screens (e.g., computer screens) need higher refresh rate (fps) to avoid flickering.
- For cinema (dark theater) and fps of 24 Hz is enough to avoid flickering.





HVS Spatial Frequency Response (SFR):

- Assumption: spatial HVS sensitivity is isotropic, the spatial frequency response can be measured along any arbitrary spatial axis.
- Spatial sensitivity normalization to the observation distance: SFR expressed as a function of the *spatial angular frequency*.











Kelly experiments

- Human observers observe vertical sinusoidal patterns of amplitude *Cs* and frequency F_x superimposed on a constant background having illumination *C*: $f(x, y) = C(1 + s \cos 2\pi F_x x).$
- When they first observe the existence of the pattern having amplitude Cs_{min}, contrast sensitivity is defined by:

 $S_e = \cdot$







Spatial HVS frequency response.





- Peak SFR is observed at about 2-5 cycles/degree.
- Cutoff spatial frequency is 30 cycles/degree.
- No details can be observed on a fast moving object.
 - SFR varies with eye motion configuration:
 - Saccadic motion allows much higher spatial HVS sensitivity.









HVS spatiotemporal frequency response experiments:

• Test pattern:

 $f(x, y, t) = C(1 + s \cos(2\pi F_x x) \cos(2\pi F_t t)).$

- For a fixed pair of F_x and F_y the modulation level *s* was changed.
- The observer was requested to determine the minimal observable modulation level s_{min} .





Contrast sensitivity.

Spatiotemporal HVS contrast sensitivity as a function of F_x , F_t for unconstrained eye motion.

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- When the temporal(spatial) frequencies are close to zero, the spatial (temporal) HVS frequency response has bandpass characteristics.
- At high temporal (spatial) frequencies, the spatial (temporal) frequency HVS response is low pass:
- Its peak response frequency reduces, when the temporal (spatial) frequency increases.

• When an object moves too quickly, the eye cannot distinguish object details (high spatial frequencies).



- HVS can discern object details (higher spatial frequencies) much better, when the object image is stationary.
- Similarly, at higher spatial frequencies the temporal response becomes low pass.
- Implication of this inverse relationship between spatial and temporal HVS responses:
 - spatial video resolution can be swapped with temporal one and vice versa.



• 2:1 Interlaced video takes advantage of HVS properties.



Sampling grids for: a) progressive; b) 2:1 interlaced video.





2:1 interlaced video:

- fast moving scenes:
 - They can be visualized at a limited frame rate, by dividing a frame into two temporally adjacent fields, each with half the number of frame lines.
- slow moving scenes:
 - the lines in two consecutive fields are perceived as one high spatial resolution video frame.





Smooth eye pursuit movement:

- Limited spatial sensitivity for fast moving objects, but eye does not.
- Observed image on eye retina, when eye moves:

$$\tilde{f}(x, y, t) = f(x + v_x t, y + v_y t, t),$$

- f(x, y, t): displayed image,
- (v_x, v_y) : eye motion velocities.





- Eye motion cancels object motion on retina.
- Details of a fast moving object can be seen by eye pursuit movement:
 - Increased spatial HVS sensitivity.





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- In many cases, humans are the final video consumers.
- Perceived video quality must be quantified.
- Video Quality (VQ) is influenced by:
 - Acquisition noise;

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- Compression effects;
- Transmission errors.
- VQ assessment can help meet video storage and transmission requirements.



Subjective video quality assessment.

- Ask humans to watch the video and assess its quality.
- *Mean Opinion Score* (*MoS*): scale [1, ..., 5].
- 1: worst, 5: best quality.
- Labor intensive and expensive.
- A large number of viewers is needed to lower score variability and provide statistical certainty.
- Impossible to assess all videos before broadcasting.
- Useful in providing a golden standard for automated VQA



Objective video quality assessment:

- No human observers involved.
- *Full reference VQA algorithms* operate on distorted video, while employing the original video reference for comparison.
- VQA measures:
 - Mean Square Error,
 - Peak Signal to Noise Ratio,
 - SSIM.



- **Reduced reference VQA algorithms** use distorted video and some original video information, e.g., edge locations.
- **Blind VQA algorithms**: no knowledge about distortion nor reference video.



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Thank you very much for your attention!

More material in http://icarus.csd.auth.gr/cvml-web-lecture-series/

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